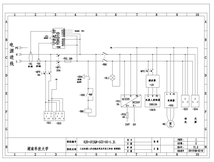

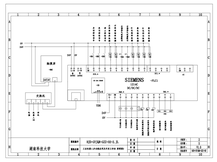

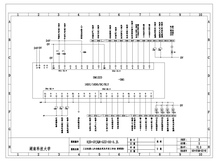

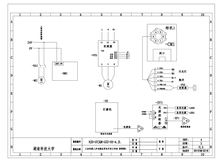

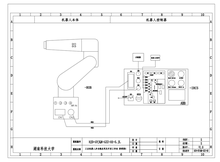

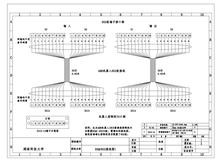

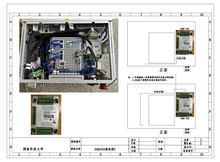

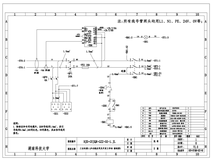

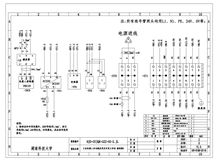

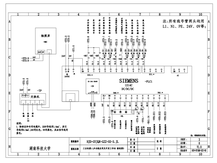

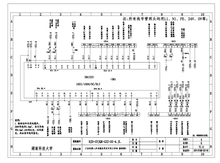

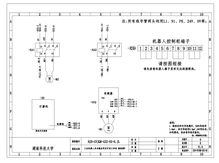

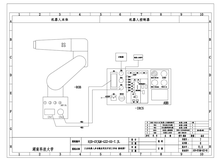

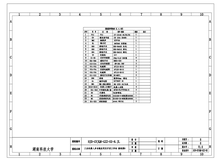

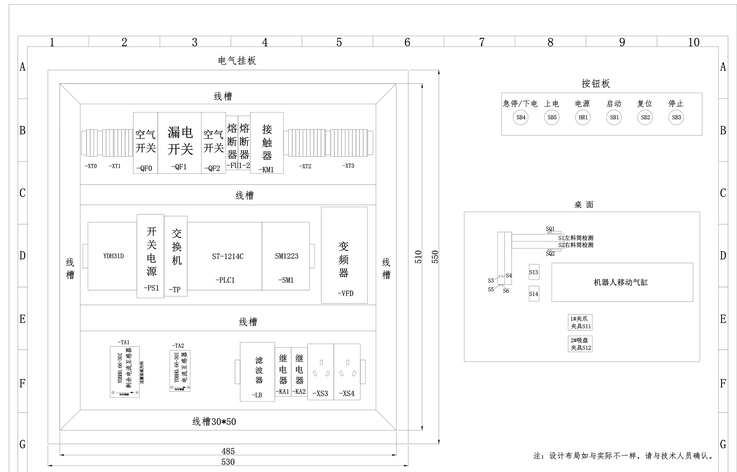
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A B C D E F G H
电气挂板
线槽
空气开关 -QF0
漏电开关 -QF1
空气开关 -QF2
熔断器 -FU1-2
接触器 -KM1
-XT0 -XT1
-XT2 -XT3
线槽
YDBS1D
开关电源 -PS1
交换机 -TP
S7-1214C -PLC1
SM1223 -SM1
变频器 -VFD
线槽
-TA1
-TA2
滤波器 -LB
继电器 -KA1
继电器 -KA2
-XS3
-XS4
线槽30*50
485
530
510
550
按钮板
急停/下电 SB4
上电 SB5
电源 HB1
启动 SB1
复位 SB2
停止 SB3
桌面
SB1
S1左料筒检测
S2右料筒检测
SB2
S3
S4
S5
S6
S13
S14
机器人移动气缸
10夹爪 夹具S11
20吸盘 夹具S12
注：设计布局如与实际不一样，请与技术人员确认。
湖南科技大学
图纸编号 HJD-GYJQR-GZZ-02-1.BJ
图纸名称 工业机器人多功能应用及开发 工作站布局图1
设 计 日 期
审 核 日 期
批 准 日 期
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